Soft Solids – Lecture 3

3 ECTS - 35h

Wednesday : 2 PM – 5:30 PM

ENS – Room L363

Matteo Ciccotti
Prof. de l'ESPCI
Laboratoire SIMM
matteo.ciccotti@espci.fr

Benoit Roman
DR CNRS
Laboratoire PMMH
benoit.roman@espci.fr

WE HAVE SEEN... 1D STRETCHABLE SOLIDS

- **Strain & stretch** $x' = \mathcal{F}(x)$ $\varepsilon(x) = \frac{dl' - dl}{dl} = \frac{du}{dx}(x) = \mathcal{F}'(x) - 1$

$$\lambda(x) \equiv \frac{dl'}{dl}(x) = \mathcal{F}'(x) = 1 + \varepsilon(x)$$

- **Stress** $\sigma(x) = \frac{F(x)}{S}$

- **The FPD** $\frac{d\sigma}{dx}(x) + f(x) = \rho a(x)$

- **Hooke's elastic law** $\sigma = \frac{d\mathcal{U}_{el}}{d\varepsilon}(\varepsilon) = E\varepsilon$

- **The elastic energy** $\mathcal{U}_{el} = \frac{1}{2}E\varepsilon^2 = \frac{1}{2}\sigma\varepsilon = \frac{1}{2}\frac{\sigma^2}{E}$

- **Elasto-dynamic equation:** $E\frac{d^2u}{dx^2}(x) + f(x) = \rho\frac{d^2u}{dx^2}$

- **Waves and oscillations** $c = \sqrt{\frac{E}{\rho}}$ $t^* \sim \frac{L}{c}$

TODAY'S MENU: 3D STRETCHABLE SOLIDS

- **Strain & stress** $\varepsilon_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$ $\vec{T}(\vec{x}) = \bar{\sigma}(\vec{x}) \vec{n}$
- **The FPD** $\overrightarrow{\text{div}} \bar{\sigma} + \vec{f} = \rho \vec{a}$
- **Hooke's elastic law** $\bar{\sigma} = \lambda(\text{Tr } \bar{\varepsilon}) \bar{I} + 2\mu \bar{\varepsilon}$
- **The elastic energy** $U_{el}(\bar{\varepsilon}) = \frac{\lambda}{2} (\text{Tr } \bar{\varepsilon})^2 + \mu \text{Tr } (\bar{\varepsilon}^2)$
- **Variational principle** $dU_p(\vec{u}) = dU_{el}(\vec{u}) - dW(\vec{u}) = 0$
- **Lamé-Navier equation:** $\rho \frac{\partial^2 \vec{u}}{\partial t^2} = \vec{f} + \mu \Delta \vec{u} + \left(K + \frac{\mu}{3} \right) \overrightarrow{\text{grad}}(\text{div } \vec{u})$
- **Analogy with Navier Stokes equation:** $\rho \frac{\partial \vec{v}}{\partial t} + \rho \vec{v} \cdot \overrightarrow{\text{grad}} \vec{v} = \rho \vec{g} - \overrightarrow{\text{grad}} p + \eta \Delta \vec{v} + \left(\kappa + \frac{\eta}{3} \right) \overrightarrow{\text{grad}} (\text{div } \vec{v})$

MODULES ELASTIQUES - MATERIAU ISOTROPE

Deux modules au choix entre les suivants:

- K Module de compressibilité
- E Module d'Young – Traction uniaxiale
- ν Rapport de Poisson – Contraction latérale en traction uniaxiale
- λ Premier coefficient de Lamé
- μ Second coefficient de Lamé – Module de cisaillement
- M Module oedométrique (Compression confinée, onde compression)

	(λ, μ)	(E, μ)	(K, λ)	(K, μ)	(λ, ν)	(μ, ν)	(E, ν)	(K, ν)	(K, E)
$K =$	$\lambda + \frac{2\mu}{3}$	$\frac{E\mu}{3(3\mu - E)}$			$\lambda \frac{1 + \nu}{3\nu}$	$\frac{2\mu(1 + \nu)}{3(1 - 2\nu)}$	$\frac{E}{3(1 - 2\nu)}$		
$E =$	$\mu \frac{3\lambda + 2\mu}{\lambda + \mu}$		$9K \frac{K - \lambda}{3K - \lambda}$	$\frac{9K\mu}{3K + \mu}$	$\frac{\lambda(1 + \nu)(1 - 2\nu)}{\nu}$	$2\mu(1 + \nu)$		$3K(1 - 2\nu)$	
$\lambda =$		$\mu \frac{E - 2\mu}{3\mu - E}$		$K - \frac{2\mu}{3}$		$\frac{2\mu\nu}{1 - 2\nu}$	$\frac{E\nu}{(1 + \nu)(1 - 2\nu)}$	$\frac{3K\nu}{1 + \nu}$	$\frac{3K(3K - E)}{9K - E}$
$\mu =$			$3 \frac{K - \lambda}{2}$		$\lambda \frac{1 - 2\nu}{2\nu}$		$\frac{E}{2 + 2\nu}$	$3K \frac{1 - 2\nu}{2 + 2\nu}$	$\frac{3KE}{9K - E}$
$\nu =$	$\frac{\lambda}{2(\lambda + \mu)}$	$\frac{E}{2\mu} - 1$	$\frac{\lambda}{3K - \lambda}$	$\frac{3K - 2\mu}{2(3K + \mu)}$					$\frac{3K - E}{6K}$
$M =$	$\lambda + 2\mu$	$\mu \frac{4\mu - E}{3\mu - E}$	$3K - 2\lambda$	$K + \frac{4\mu}{3}$	$\lambda \frac{1 - \nu}{\nu}$	$\mu \frac{2 - 2\nu}{1 - 2\nu}$	$E \frac{1 - \nu}{(1 + \nu)(1 - 2\nu)}$	$3K \frac{1 - \nu}{1 + \nu}$	$3K \frac{3K + E}{9K - E}$

MODULES D'YOUNG ET RAPPORT DE POISSON

$$E = \frac{\sigma}{\varepsilon_{\parallel}} \quad \text{Module d'Young}$$

$$\nu = -\frac{\varepsilon_{\perp}}{\varepsilon_{\parallel}} \quad \text{Rapport de Poisson}$$

$$-1 < \nu < 1/2$$

$$\left\{ \begin{array}{l} \varepsilon_{11} = \frac{1}{E} [\sigma_{11} - \nu(\sigma_{22} + \sigma_{33})] \\ \varepsilon_{22} = \frac{1}{E} [\sigma_{22} - \nu(\sigma_{11} + \sigma_{33})] \\ \varepsilon_{33} = \frac{1}{E} [\sigma_{33} - \nu(\sigma_{11} + \sigma_{22})] \\ \varepsilon_{12} = \frac{\sigma_{12}}{2\mu} \quad \varepsilon_{13} = \frac{\sigma_{13}}{2\mu} \quad \varepsilon_{23} = \frac{\sigma_{23}}{2\mu} \end{array} \right.$$

Traction uniaxiale

$$\bar{\varepsilon} = \frac{1 + \nu}{E} \bar{\sigma} - \frac{\nu}{E} \text{Tr}(\bar{\sigma}) \bar{I}$$

$$\varepsilon_{ij} = \frac{1 + \nu}{E} \sigma_{ij} - \frac{\nu}{E} \sigma_{kk} \delta_{ij}$$

$$\lambda = \frac{\nu E}{(1 + \nu)(1 - 2\nu)}$$

$$\mu = \frac{E}{2(1 + \nu)}$$

MODULES DE COMPRESSIBILITE ET CISAILLEMENT

Décomposition en sphérique et déviateur

$$\varepsilon_{ij} = \frac{\varepsilon_{kk}}{3}\delta_{ij} + \left(\varepsilon_{ij} - \frac{\varepsilon_{kk}}{3}\delta_{ij} \right) \quad \bar{\bar{\varepsilon}} = \bar{\bar{S}}_\varepsilon - \bar{\bar{D}}_\varepsilon = \varepsilon_m \bar{\bar{\delta}} + \varepsilon_d \bar{\bar{\pi}}_\varepsilon$$

$$\sigma_{ij} = \lambda \varepsilon_{kk} \delta_{ij} + 2\mu \varepsilon_{ij} = K \varepsilon_{kk} \delta_{ij} + 2\mu \left(\varepsilon_{ij} - \frac{\varepsilon_{kk}}{3} \delta_{ij} \right)$$

$$K = \lambda + \frac{2}{3}\mu \quad \text{Module de compressibilité}$$

$$\bar{\bar{\sigma}} = \bar{\bar{S}}_\sigma + \bar{\bar{D}}_\sigma = \sigma_m \bar{\bar{\delta}} + \sigma_d \bar{\bar{\pi}}_\sigma$$

$$\bar{\bar{S}}_\sigma = 3K \bar{\bar{S}}_\varepsilon \quad \bar{\bar{D}}_\sigma = 2\mu \bar{\bar{D}}_\varepsilon \quad \bar{\bar{\pi}}_\sigma = \bar{\bar{\pi}}_\varepsilon$$

Découplage

$$\sigma_m = 3K \varepsilon_m = K(dV/V) \quad \text{Module de compressibilité}$$

$$K = \frac{-dP}{\frac{dV}{V}} = -V \frac{dP}{dV}$$

$$\sigma_d = 2\mu \varepsilon_d \quad \text{Module de cisaillement}$$

ELASTICITE' 2D (SYMETRIE EN x_3)

1) Déformation plane (objets très épais en x_3)

$$u_3 = 0 \quad u_1, u_2 \text{ indep. de } x_3 \quad \varepsilon_{ij} = 1/2(\partial u_i/x_j + \partial u_j/x_i)$$

$$\varepsilon_{33} = \varepsilon_{13} = \varepsilon_{23} = 0$$

$$\varepsilon_{11}, \varepsilon_{22}, \varepsilon_{12} \text{ indépendant de } x_3$$

$$\varepsilon_{33} = 1/E(\sigma_{33} - \nu(\sigma_{11} + \sigma_{22})) = 0 \quad \text{Hooke}$$

$$\sigma_{33} = \nu(\sigma_{11} + \sigma_{22})$$

$$\underline{\underline{\varepsilon}} = \begin{pmatrix} \varepsilon_{11} & \varepsilon_{12} & 0 \\ \varepsilon_{12} & \varepsilon_{22} & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \underline{\underline{\sigma}} = \begin{pmatrix} \sigma_{11} & \sigma_{12} & 0 \\ \sigma_{12} & \sigma_{22} & 0 \\ 0 & 0 & \nu(\sigma_{11} + \sigma_{22}) \end{pmatrix}$$

$$\begin{cases} \varepsilon_{11} = \frac{1}{E'}(\sigma_{11} - \nu'\sigma_{22}) \\ \varepsilon_{22} = \frac{1}{E'}(\sigma_{22} - \nu'\sigma_{11}) \\ \varepsilon_{12} = \frac{\sigma_{12}}{2\mu} \end{cases} \quad E' = \frac{E}{1 - \nu^2} \quad \nu' = \frac{\nu}{1 - \nu} \quad \text{Modules effectifs}$$

ELASTICITE' 2D (SYMETRIE EN x_3)

2) Contrainte plane (objets très fins en x_3)

$$\sigma_{33} = \sigma_{13} = \sigma_{23} = 0$$

$\sigma_{11}, \sigma_{22}, \sigma_{12}$ indépendant de x_3

$$\left\{ \begin{array}{l} \varepsilon_{11} = \frac{1}{E}(\sigma_{11} - \nu\sigma_{22}) \\ \varepsilon_{22} = \frac{1}{E}(\sigma_{22} - \nu\sigma_{11}) \\ \varepsilon_{12} = \frac{\sigma_{12}}{2\mu} \end{array} \right. \quad \text{Hooke} \quad \mu = \frac{E}{2(1+\nu)}$$
$$\varepsilon_{33} = -\frac{\nu}{E}(\sigma_{11} + \sigma_{22}) = -\frac{\nu}{1-\nu}(\varepsilon_{11} + \varepsilon_{22})$$
$$\varepsilon_{23} = 0 \quad \varepsilon_{13} = 0$$

$$\bar{\bar{\sigma}} = \begin{pmatrix} \sigma_{11} & \sigma_{12} & 0 \\ \sigma_{12} & \sigma_{22} & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\bar{\bar{\varepsilon}} = \begin{pmatrix} \varepsilon_{11} & \varepsilon_{12} & 0 \\ \varepsilon_{12} & \varepsilon_{22} & 0 \\ 0 & 0 & -\frac{\nu}{1-\nu}(\varepsilon_{11} + \varepsilon_{22}) \end{pmatrix}$$

$$E' = E \quad \nu' = \nu$$

Modules
effectifs

3.5.1 L'EQUATION DE LAMÉ-NAVIER

Equation élasto-dynamique pour un milieu élastique linéaire isotrope:

$$\left\{ \begin{array}{l} \overrightarrow{\text{div}} \overline{\overline{\sigma}} + \overrightarrow{f} - \rho \overrightarrow{\gamma} = 0 \\ \overline{\overline{\sigma}} = \lambda(\text{Tr } \overline{\overline{\varepsilon}}) \overline{I} + 2\mu \overline{\overline{\varepsilon}} \\ \overline{\overline{\varepsilon}} = \frac{\overrightarrow{\text{grad}} \overrightarrow{u} + {}^t \overrightarrow{\text{grad}} \overrightarrow{u}}{2} \end{array} \right. \quad \begin{array}{l} \text{Loi fondamentale de la dynamique} \\ \text{Loi de Hooke} \\ \text{Déformation en termes} \\ \text{de déplacement} \end{array}$$

$$(\lambda + \mu) \overrightarrow{\text{grad}}(\text{div } \overrightarrow{u}) + \mu \Delta \overrightarrow{u} + \overrightarrow{f} = \rho \frac{\partial^2 \overrightarrow{u}}{\partial t^2}$$

Une expression alternative de la même équation:

$$(\lambda + \mu) \overrightarrow{\text{rot}}(\overrightarrow{\text{rot}} \overrightarrow{u}) + (\lambda + 2\mu) \Delta \overrightarrow{u} + \overrightarrow{f} = \rho \frac{\partial^2 \overrightarrow{u}}{\partial t^2}$$

3.5.2 ONDES DE VOLUME ($\lambda \ll L^*$)

En l'absence de forces de volume on peut propager deux types d'ondes:

$$(\lambda + \mu) \overrightarrow{\text{rot}}(\overrightarrow{\text{rot}} \vec{u}) + (\lambda + 2\mu) \Delta \vec{u} + \cancel{\vec{f}} = \rho \frac{\partial^2 \vec{u}}{\partial t^2} \quad \vec{f} = \vec{0}$$

$$(\lambda + \mu) \overrightarrow{\text{grad}}(\text{div} \vec{u}) + \mu \Delta \vec{u} + \cancel{\vec{f}} = \rho \frac{\partial^2 \vec{u}}{\partial t^2} \quad \vec{u} = \vec{u}_L + \vec{u}_T$$

Ondes **L**ongitudinales (compression)

$$\text{div} \vec{u}_L \neq 0 \quad \overrightarrow{\text{rot}} \vec{u}_L = 0$$

$$(\lambda + 2\mu) \Delta \vec{u}_L = \rho \frac{\partial^2 \vec{u}_L}{\partial t^2}$$

$$V_L = \sqrt{\frac{\lambda + 2\mu}{\rho}} = \sqrt{\frac{E'}{\rho}} \quad E' = \frac{E(1 - \nu)}{(1 + \nu)(1 - 2\nu)} = M$$

Ondes **T**ransversales (cisaillement)

$$\text{div} \vec{u}_T = 0 \quad \overrightarrow{\text{rot}} \vec{u}_T \neq 0$$

$$\mu \Delta \vec{u}_T = \rho \frac{\partial^2 \vec{u}_T}{\partial t^2}$$

$$V_T = \sqrt{\frac{\mu}{\rho}} = \sqrt{\frac{E'}{\rho}} \quad E' = \frac{E}{2(1 + \nu)}$$

u Polarisation **k** Vecteur d'onde **V** Célérité de l'onde

TODAY'S MENU: 3D STRETCHABLE SOLIDS

- **Strain & stress** $\varepsilon_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$ $\vec{T}(\vec{x}) = \bar{\sigma}(\vec{x}) \vec{n}$
- **The FPD** $\overrightarrow{\text{div}} \bar{\sigma} + \vec{f} = \rho \vec{a}$
- **Hooke's elastic law** $\bar{\sigma} = \lambda(\text{Tr } \bar{\varepsilon}) \bar{I} + 2\mu \bar{\varepsilon}$
- **The elastic energy** $U_{el}(\bar{\varepsilon}) = \frac{\lambda}{2} (\text{Tr } \bar{\varepsilon})^2 + \mu \text{Tr } (\bar{\varepsilon}^2)$
- **Variational principle** $dU_p(\vec{u}) = dU_{el}(\vec{u}) - dW(\vec{u}) = 0$
- **Lamé-Navier equation:** $\rho \frac{\partial^2 \vec{u}}{\partial t^2} = \vec{f} + \mu \Delta \vec{u} + \left(K + \frac{\mu}{3} \right) \overrightarrow{\text{grad}}(\text{div } \vec{u})$
- **Analogy with Navier Stokes equation:** $\rho \frac{\partial \vec{v}}{\partial t} + \rho \vec{v} \cdot \overrightarrow{\text{grad}} \vec{v} = \rho \vec{g} - \overrightarrow{\text{grad}} p + \eta \Delta \vec{v} + \left(\kappa + \frac{\eta}{3} \right) \overrightarrow{\text{grad}} (\text{div } \vec{v})$

IMPACT ON A WATER DROP

Clanet et al., J. Fluid Mech (2004) 517, 199