

Application of averaging technique for the numerical simulation of highly oscillatory problems

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"Space-Time Multiscale Methods", Paris, June 5, 2018

Highly-oscillatory problems with periodic time-dependence

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We consider a highly oscillatory problem in a (functional) Banach space X :

$$\begin{aligned}
 (\mathcal{P}_\varepsilon) \quad \frac{d}{dt}u^\varepsilon(t) &= f_{t/\varepsilon}(u^\varepsilon(t)), \quad u^\varepsilon(t) \in X, \\
 u^\varepsilon(0) &= u_0 \in X,
 \end{aligned}$$

where

- ε is a possibly small parameter (scales as the inverse of a frequency).
- $(\theta, u) \mapsto f_\theta(u)$ is given, smooth and P -periodic with respect to θ .

Numerical difficulties: Standard schemes lead to $\|u^\varepsilon - u^{\varepsilon, \Delta t}\| \leq C \frac{(\Delta t)^p}{\varepsilon^q}$, $q > 0$, forcing $\Delta t \leq \varepsilon$ and thus formidable costs for small values of ε .

Partial remedy: Averaging methods lead to $\|u^\varepsilon - u^{\varepsilon, \Delta t}\| \leq C((\Delta t)^p + \varepsilon^q)$.

Aim: Construct a numerical method which is **uniformly accurate** with respect to ε , i.e. such that $\|u^\varepsilon - u^{\varepsilon, \Delta t}\| \leq C(\Delta t)^p$ with C independent of ε .

Examples

Our examples are of the form

$$\frac{d}{dt}y^\varepsilon = \frac{1}{\varepsilon}Ay^\varepsilon + f(y^\varepsilon)$$

where $\theta \mapsto e^{A\theta}$ is periodic with respect to θ .

To filter out the highly oscillatory dynamics, we introduce the unknown

$$u^\varepsilon(t) = e^{-At/\varepsilon}y^\varepsilon(t)$$

which satisfies

$$\frac{d}{dt}u^\varepsilon = e^{-At/\varepsilon}f\left(e^{At/\varepsilon}u^\varepsilon(t)\right) = f_{t/\varepsilon}(u^\varepsilon(t))$$

Here we have

$$f_\theta(u) = e^{-A\theta}f\left(e^{A\theta}u^\varepsilon(t)\right)$$

Examples (ii)

- Transport in graphene in semiclassical regime
- Schrödinger equation and Gross-Pitaevskii equation

$$i\partial_t\psi^\varepsilon = -\frac{1}{\varepsilon}\Delta\psi^\varepsilon + \alpha|\psi^\varepsilon|^2\psi^\varepsilon \quad \text{with periodic boundary conditions}$$

$$i\partial_t\psi^\varepsilon = -\frac{1}{\varepsilon}\Delta\psi^\varepsilon + \frac{\omega}{\varepsilon}|x|^2\psi^\varepsilon + \alpha|\psi^\varepsilon|^2\psi^\varepsilon \quad \text{on } \mathbb{R}^d$$

- The nonlinear Klein-Gordon equation in the nonrelativistic regime

$$\varepsilon\partial_{tt}u^\varepsilon - \Delta u^\varepsilon + \frac{1}{\varepsilon}u^\varepsilon + f(u^\varepsilon) = 0, \quad x \in \mathbb{R}^d, \quad t > 0,$$

- Vlasov equation in a strong magnetic field

$$\partial_t f^\varepsilon + v \cdot \nabla_x f^\varepsilon + E \cdot \nabla_v f^\varepsilon + \frac{v \times B}{\varepsilon} \cdot \nabla_v f^\varepsilon = 0$$

- non relativistic limit of nonlinear Dirac equation

Averaging result (case of the so-called stroboscopic averaging)

Averaging methods assert that for all $k \in \mathbb{N}^*$ there exist

- a P -periodic **change of variables**

$$(\tau, u) \in \mathbb{T} \times X \mapsto \Phi_\tau^{[k]}(u) \in X \quad \text{with } \Phi_0^{[k]}(u) = u$$

- a **smooth, autonomous** vector field $F^{[k]}$ and its flow-map $\Psi_t^{[k]}$

- $u \in X \mapsto F^{[k]}(u) \in X$

- $(t, u) \mapsto \Psi_t^{[k]}(u) \in X \quad \frac{d}{dt} \Psi_t^{[k]}(u) = F^{[k]}(\Psi_t^{[k]}(u)), \quad \Psi_0^{[k]}(u) = u$

such that

$$\forall t \in [0, T], \quad \left\| u^\varepsilon(t) - \Phi_{\frac{t}{\varepsilon}}^{[k]} \circ \Psi_t^{[k]}(u_0) \right\|_X \leq C\varepsilon^{k+1}.$$

↑ ↑

high-oscillations slow drift

ref.: Bogoliubov-Mitropolsky 1930', Perko 1968, ...

and their adaptation to PDEs: JFOCM 15, Castella-Chartier-M.-Murua

Averaging: an assessment

The standard use of averaging method consist in the simulation of

$$\frac{d}{dt}\Psi_t^{[k]} = F^{[k]}(\Psi_t^{[k]})$$

complemented with the computation of $\Phi_\theta^{[k]}$.

Pros of averaging

- models are **non-stiff** and do not suffer from severe constraints on the time step when ε is small
- **preserve** part or all **geometric structures**

Cons

- methods based on the (numerical or not) computation of the averaged vector field $F^{[k]}$ lead to an incompressible error term $\mathcal{O}(\varepsilon^{k+1})$ owing to the truncation of the series
- for values of ε away from 0 one needs to include many terms in the expansion leading to important costs

New approach: averaging with corrections (i)

Our approach, in the **micro/macro** spirit, consists in adding an equation to the averaged equation. The unknown is split as follows:

$$u^\varepsilon(t) = \Phi_{t/\varepsilon}^{[k]} \left(\Psi_t^{[k]} \right) + w^\varepsilon(t)$$

where $\Psi_t^{[k]}$ solves the **macro (averaged) equation**

$$\frac{d}{dt} \Psi_t^{[k]} = F^{[k]}(\Psi_t^{[k]}), \quad \Psi_0^{[k]} = u_0.$$

The remainder w^ε solves the micro equation

$$\begin{aligned} \frac{d}{dt} w^\varepsilon(t) &= f_{t/\varepsilon} \left(\Phi_{t/\varepsilon}^{[k]} \left(\Psi_t^{[k]} \right) + w^\varepsilon(t) \right) - \left(\frac{1}{\varepsilon} \partial_\theta \Phi_{t/\varepsilon}^{[k]} - \partial_u \Phi_{t/\varepsilon}^{[k]} F^{[k]} \right) \left(\Psi_t^{[k]} \right), \\ w^\varepsilon(0) &= 0. \end{aligned}$$

Theorem

$$\forall \varepsilon \in]0, 1], \quad \forall 0 \leq s \leq k + 1, \quad \forall t \in [0, T], \quad \left\| \frac{d^s}{dt^s} w^\varepsilon \right\| \leq C \varepsilon^{k+1-s}$$

Advantages of this method

- 1 It is clear that if Ψ^ε and w^ε satisfy the micro/macro equations, then $u^\varepsilon(t) = \Phi_{t/\varepsilon}^{[k]}(\Psi_t^\varepsilon(u_0)) + w^\varepsilon(t)$ satisfies the original equation

$$\frac{d}{dt}u^\varepsilon(t) = f_{t/\varepsilon}(u^\varepsilon(t)).$$

In contrast with usual averaging, our micro/macro method is **not an approximation** and contains whole the information of the original problem.

- 2 The fact that w^ε has bounded time-derivatives with respect to ε allows to use standard numerical methods for the micro/macro system with **uniform accuracy** with respect to ε .

Take-away message:

A p -th order standard scheme is uniformly accurate of order p when applied to the micro-macro system provided $\Phi^{[p]}$ and $F^{[p]}$ are used.

Numerical tests for the Hénon-Heiles model

It is a Hamiltonian system, for the unknown (q_1, q_2, p_1, p_2) with

$$H(p, q) = \frac{p_1^2}{2\varepsilon} + \frac{p_2^2}{2} + \frac{q_1^2}{2\varepsilon} + \frac{q_2^2}{2} + q_1^2 q_2 - \frac{1}{3} q_2^3.$$

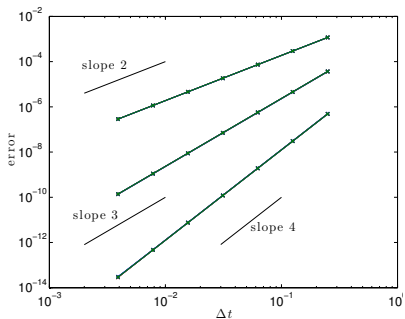
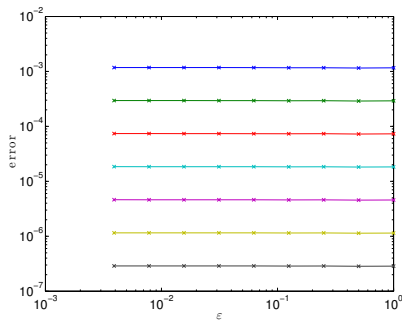
When ε is small, the variables $(q_1^\varepsilon, p_1^\varepsilon)$ is highly oscillatory:

$$\left\{ \begin{array}{l} \dot{q}_1^\varepsilon = \frac{p_1^\varepsilon}{\varepsilon} \\ \dot{q}_2^\varepsilon = p_2^\varepsilon \\ \dot{p}_1^\varepsilon = -\frac{q_1^\varepsilon}{\varepsilon} - 2q_1^\varepsilon q_2^\varepsilon \\ \dot{p}_2^\varepsilon = -q_2^\varepsilon - (q_1^\varepsilon)^2 + (q_2^\varepsilon)^2 \end{array} \right.$$

We test the following numerical methods:

- Our second order method: UA of order 2
- A third order method constructed with $\Phi^{[2]}$ and $F^{[2]}$ by extrapolation: UA of order 3
- A fourth order method constructed with $\Phi^{[3]}$ and $F^{[3]}$ by extrapolation: UA of order 4

OUR UA SCHEMES (ORDERS 2, 3 AND 4)

(a) Error with respect to Δt (b) Error with respect to ϵ , scheme of order 2

THANK YOU FOR YOUR ATTENTION