

# Master M1 (ICFP): Numerical Methods for Partial Differential Equations

## Midterm 2019

Here are three timestepping schemes for solving the ordinary differential equation  $\frac{du}{dt} = f(u)$

$$\text{Crank Nicolson} \quad u_{n+1} = u_n + \frac{\Delta t}{2} (f(u_n) + f(u_{n+1})) \quad (1)$$

$$\text{Midpoint} \quad u_{n+1} = u_n + \Delta t f \left( u_n + \frac{\Delta t}{2} f(u_n) \right) \quad (2)$$

$$\text{Leapfrog} \quad u_{n+1} = u_{n-1} + 2\Delta t f(u_n) \quad (3)$$

1) Use Taylor series expansions of the exact and approximate solutions about  $u_n$  to show that all three methods are second-order accurate, i.e. that the single-step error is proportional to  $(\Delta t)^3$ . Find the constant of proportionality (the constant multiplying  $(\Delta t)^3$ ) for each of the three methods. You may treat only the differential equation

$$\frac{du}{dt} = \lambda u \quad (4)$$

i.e. you do not need to consider the case of a general  $f(u)$ .

Exact solution:

$$u_{n+1} = e^{\lambda \Delta t} u_n = \left[ 1 + \lambda \Delta t + \frac{1}{2}(\lambda \Delta t)^2 + \frac{1}{6}(\lambda \Delta t)^3 \dots \right] u_n$$

Crank-Nicolson:

$$\begin{aligned} u_{n+1} &= \frac{1 + \frac{\lambda \Delta t}{2}}{1 - \frac{\lambda \Delta t}{2}} u_n \\ &= \left( 1 + \frac{\lambda \Delta t}{2} \right) \left( 1 + \frac{\lambda \Delta t}{2} + \left( \frac{\lambda \Delta t}{2} \right)^2 + \left( \frac{\lambda \Delta t}{2} \right)^3 + \dots \right) \\ &= 1 + 2 \left( \frac{\lambda \Delta t}{2} \right) + 2 \left( \frac{\lambda \Delta t}{2} \right)^2 + 2 \left( \frac{\lambda \Delta t}{2} \right)^3 + \dots \end{aligned}$$

The first non-matching term is that in  $(\lambda \Delta t)^3$  and the error is

$$\left( \frac{1}{4} - \frac{1}{6} \right) (\lambda \Delta t)^3 = \frac{1}{12} (\lambda \Delta t)^3$$

Midpoint method:

$$\begin{aligned} u_{n+1} &= u_n + \lambda \Delta t \left( u_n + \frac{\lambda \Delta t}{2} u_n \right) \\ &= 1 + \lambda \Delta t + \frac{1}{2} (\lambda \Delta t)^2 \end{aligned}$$

This series has no term in  $(\lambda\Delta t)^3$ . The error is

$$\left(0 - \frac{1}{6}\right) (\lambda\Delta t)^3 = -\frac{1}{6}(\lambda\Delta t)^3$$

Leapfrog:

$$\begin{aligned} u_{n+1} &= u_{n-1} + 2\lambda\Delta t u_n \\ &= u_n - \lambda\Delta t u_n + \frac{1}{2}(\lambda\Delta t)^2 u_n - \frac{1}{6}(\lambda\Delta t)^3 u_n + \dots + 2\lambda\Delta t u_n \\ &= u_n + \lambda\Delta t u_n + \frac{1}{2}(\lambda\Delta t)^2 u_n - \frac{1}{6}(\lambda\Delta t)^3 u_n + \dots \end{aligned}$$

The first non-matching term is that in  $(\lambda\Delta t)^3$  and the error is

$$\left(-\frac{1}{6} - \frac{1}{6}\right) (\lambda\Delta t)^3 = -\frac{1}{3}(\lambda\Delta t)^3$$

**2)** We now consider the stability of the three methods for the diffusion and the wave equation. You may use the result that the general solution to a linear constant-coefficient difference equation

$$0 = a_1 u_{n+1} + a_0 u_n + a_{-1} u_{n-1} + a_{-2} u_{n-2} + a_{-3} u_{n-3} \dots \quad (5)$$

is a linear combination of solutions of the form

$$u_n = cr^n \quad (6)$$

**2a)** For the diffusion equation, we consider (4) for  $\lambda = -k^2$  real and negative, motivated by

$$\begin{aligned} \partial_t u &= \partial_{xx} u & u(x, t) &= \hat{u}(t) e^{ikx} \\ \frac{d\hat{u}}{dt} &= -k^2 \hat{u} & \hat{u}(t) &= e^{-k^2 t} \hat{u}(0) \end{aligned} \quad (7)$$

For the three methods, find the constraint on  $\Delta t > 0$  such that the numerical sequence  $u_n$  decays when integrating (4) with  $\lambda$  real and negative.

Crank-Nicolson:

$$u_{n+1} = \frac{1 + \frac{\lambda\Delta t}{2}}{1 - \frac{\lambda\Delta t}{2}} u_n = \frac{1 - \frac{k^2\Delta t}{2}}{1 + \frac{k^2\Delta t}{2}} u_n$$

We require

$$\left|1 - \frac{k^2\Delta t}{2}\right| < \left|1 + \frac{k^2\Delta t}{2}\right|$$

If  $-1 \leq k^2\Delta t \leq 1$ , then we require

$$-k^2\Delta t < k^2\Delta t$$

If  $k^2 \Delta t > 1$ , then we require

$$\frac{k^2 \Delta t}{2} - 1 < 1 + \frac{k^2 \Delta t}{2}$$

$$-1 < 1$$

which is satisfied for all  $\Delta t > 0$ . So Crank-Nicolson is always stable for the heat equation.

Midpoint method:

$$u_{n+1} = \left( 1 + \lambda \Delta t + \frac{1}{2} (\lambda \Delta t)^2 \right) u_n$$

$$= 1 - k^2 \Delta t + \frac{1}{2} (-k^2 \Delta t)^2$$

We require

$$\left| 1 - k^2 \Delta t + \frac{1}{2} (k^2 \Delta t)^2 \right| < 1$$

From the graph, we see that this inequality is satisfied as long as  $0 < k^2 \Delta t < 2$  and it is in this range of  $\Delta t$  that the midpoint method is stable for the heat equation.

Leapfrog method:

$$u_{n+1} = u_{n-1} + 2\lambda \Delta t u_n$$

Writing  $u_n = cr^n$ , we have

$$r^2 = 1 + 2\lambda \Delta t r$$

$$0 = r^2 - 2\lambda \Delta t r - 1$$

$$r_{\pm} = \lambda \Delta t \pm \sqrt{(\lambda \Delta t)^2 + 1}$$

For stability, we need  $|r_{\pm}| < 1$  for both values of  $r$  when  $\lambda = -k^2 < 0$ . From the graph supplied, we see that  $r_+ > 1$  for  $\lambda > 0$  and  $r_- < -1$  for  $\lambda < 0$  so this method is never stable.

**2b)** For the wave equation, we consider (4) for  $\lambda = ik$  imaginary. motivated by

$$\begin{aligned} \partial_t u &= \partial_x u & u(x, t) &= \hat{u}(t) e^{ikx} \\ \frac{d\hat{u}}{dt} &= ik \hat{u} & \hat{u}(t) &= e^{ikt} \hat{u}(0) \end{aligned} \quad (8)$$

For the three methods, find the constraint on  $\Delta t > 0$  such that the numerical sequence  $u_n$  retains the same amplitude when integrating (4) with  $\lambda$  imaginary.

Crank-Nicolson:

$$u_{n+1} = \frac{1 + \frac{\lambda \Delta t}{2}}{1 - \frac{\lambda \Delta t}{2}} u_n = \frac{1 + \frac{ik \Delta t}{2}}{1 - \frac{ik \Delta t}{2}} u_n$$

We require

$$\left|1 + \frac{ik\Delta t}{2}\right| = \left|1 - \frac{ik\Delta t}{2}\right|$$

This is true for all values of  $\Delta t$ . So Crank-Nicolson is always stable for the wave equation.

Midpoint method:

$$\begin{aligned} u_{n+1} &= \left(1 + \lambda\Delta t + \frac{1}{2}(\lambda\Delta t)^2\right) u_n \\ &= 1 + ik\Delta t + \frac{1}{2}(ik\Delta t)^2 \end{aligned}$$

We require

$$\begin{aligned} 1 &= \left|1 + ik\Delta t - \frac{1}{2}(k\Delta t)^2\right| \\ &= \left(1 - \frac{1}{2}(k\Delta t)^2\right)^2 + (k\Delta t)^2 \\ &= 1 - (k\Delta t)^2 + \frac{1}{4}(k\Delta t)^4 + (k\Delta t)^2 \\ &= 1 + \frac{1}{4}(k\Delta t)^4 \end{aligned}$$

This is only true when  $\Delta t = 0$ . So the midpoint method is never stable for the wave equation.

Leapfrog method:

We have  $u_n \sim r^n$  with

$$r_{\pm} = \lambda\Delta t \pm \sqrt{(\lambda\Delta t)^2 + 1}$$

For stability, we need  $|r_{\pm}| = 1$  for both values of  $r$  when  $\lambda = ik$ .

$$r_{\pm} = ik\Delta t \pm \sqrt{(ik\Delta t)^2 + 1} = ik\Delta t \pm \sqrt{1 - (k\Delta t)^2}$$

For  $|k\Delta t| < 1$ , the square root is real and we have

$$|r_{\pm}|^2 = (k\Delta t)^2 + (1 - (k\Delta t)^2) = 1$$

For  $|k\Delta t| > 1$ , the square root is imaginary and we have

$$\begin{aligned} r_{\pm} &= ik\Delta t \pm i\sqrt{(k\Delta t)^2 - 1} \\ |r_{\pm}| &= |k\Delta t \pm \sqrt{(k\Delta t)^2 - 1}| \end{aligned}$$

From the graphs, we can see that  $r_+ > 1$  for  $|k\Delta t| > 1$  and  $r_- < 1$  for  $|k\Delta t| < -1$ , leading to instability. Thus, we require  $|k\Delta t| < 1$  for stability.

To solve the diffusion equation, we can use the Crank-Nicolson method with any value of  $\Delta t$  or the midpoint method with  $\Delta t < 2/k^2$ . To solve the wave equation, we can use the Crank-Nicolson method with any value of  $\Delta t$  or the leapfrog method with  $\Delta t < 1/|k|$ .